

Remember Stoke's theorem: if \mathcal{S} is an oriented surface and $\partial\mathcal{S}$ has the boundary orientation then if \mathbf{F} is a vector field with continuous partial derivative then $\iint_{\mathcal{S}} \nabla \times \mathbf{F} \cdot d\mathbf{S} = \oint_{\partial\mathcal{S}} \mathbf{F} \cdot dr$.

- Let \mathbf{F} be the vector field $\langle x, y, xyz \rangle$ and let S be the part of the plane $2x + y + z = 2$ that lies in the first octant oriented upwards. Verify that Stoke's theorem holds in this example by explicitly computing $\iint_S \nabla \times \mathbf{F} \cdot dS$ and $\oint_{\partial S} \mathbf{F} \cdot dr$.
 - Let S_1 be the surface $x^2 + y^2 + 4z^2 = 4$ where $z \geq 0$ and let S_2 be the surface $z = 4 - x^2 - y^2$ where $z \geq 0$, where each surface is oriented with the normal pointed upwards. If \mathbf{F} is a vector field with continuous partial derivatives explain why $\iint_{S_1} \nabla \times \mathbf{F} \cdot dS = \iint_{S_2} \nabla \times \mathbf{F} \cdot dS$.
 - (a) Let D be the disc $x^2 + y^2 \leq 4$ with upward pointing orientation and let \mathbf{F} be the vector field $\mathbf{F} = \langle xz \sin(yz), \cos(yz), e^{x^2+y^2} \rangle$. What is $\iint_D \mathbf{F} \cdot dS$?
(b) Let S be the part of the paraboloid $z = 4 - x^2 - y^2$ with $z \geq 0$ with downward pointing orientation. What is $\iint_S \mathbf{F} \cdot dS$ (here \mathbf{F} is the vector field from the previous part of the problem)? **Hint:** Does \mathbf{F} have a vector potential?.
 - Let W be the part of the solid cylinder $x^2 + y^2 \leq 1$ where $0 \leq z \leq 1$, let ∂W be the boundary of this solid with the outwards pointing orientation, and let $\mathbf{F} = \langle xy, yz, xz \rangle$.
 - Directly compute $\iint_{\partial W} \mathbf{F} \cdot dS$.
 - Directly compute $\iiint_W \operatorname{div} \mathbf{F} dV$.
 - Compare your answers—what do you notice?

1.

$$z = 2 - 2x - y \quad S(x, y) = (x, y, 2 - 2x - y)$$

$$\vec{F} = (x, y, xy^2)$$

$$\nabla \times \vec{F} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \partial_x & \partial_y & \partial_z \\ x & y & xy^2 \end{vmatrix} = (xz, -yz, 0)$$

$$-\mathbf{C}_1: (t, 2-2t, 0) \quad [0, 1]$$

$$-\mathbf{C}_2: (0, t, 2-t) \quad [0, 2]$$

$$\mathbf{C}_3: (t, 0, 2-2t) \quad [0, 1]$$

$$\iint_S (\nabla \times \vec{F}) \cdot d\vec{S} = \int_0^1 \int_0^{2-2x} (x(2-2x-y), -y(2-2x-y), 0) \cdot \vec{N} dy dx$$

↓

where $\vec{\partial_x S} = (1, 0, -2)$, $\vec{\partial_y S} = (0, 1, -1)$

$$\Rightarrow \vec{N} = \vec{\partial_x S} \times \vec{\partial_y S} = (2, 1, 1)$$

$$= \int_0^1 \int_0^{2-2x} 4x - 4x^2 - 2y + y^2 dy dx = 0$$

On the other hand,

$$\int_{\partial S} \vec{F} \cdot d\vec{\sigma} = - \int_0^1 (t, 2-t, 0) \cdot (1, -2, 0) dt - \int_0^2 (0, t, 0) \cdot (0, 1, -t) dt$$

$$\begin{aligned}
& + \int_0^1 (t, 0, 0) \cdot (1, 0, -2) dt \\
& = \int_0^1 \cancel{-t} + 2(2-2t) dt - \int_0^2 t dt + \cancel{\int_0^1 1 dt} \\
& = 4 - 4 \underbrace{\int_0^1 t dt}_{\frac{1}{2}} - \underbrace{\int_0^2 t dt}_{2} = 0, \text{ as desired.}
\end{aligned}$$

2. We see by taking $z=0$ that both S_1, S_2 are bounded by the circle $x^2 + y^2 = 4$, both with positively oriented (i.e. CCW) boundary.

Thus by Stokes' theorem,

$$\iint_{S_1} (\nabla \times \vec{F}) \cdot d\vec{S} = \oint_{\partial S_1} \vec{F} \cdot d\vec{\sigma} = \oint_{\partial S_2} \vec{F} \cdot d\vec{\sigma} = \iint_{S_2} (\nabla \times \vec{F}) \cdot d\vec{S}.$$

$$\begin{aligned}
3a. \quad & \iint_D \vec{F} \cdot d\vec{S} & D(x, y) = (x, y, 0) \\
& \downarrow & \partial_x D = (1, 0, 0), \quad \partial_y D = (0, 1, 0) \\
& & \vec{N} = (0, 0, 1)
\end{aligned}$$

$$\begin{aligned}
& = \iint_D (0, 1, e^{x^2+y^2}) \cdot (0, 0, 1) dA \stackrel{\text{polar}}{=} \int_0^{2\pi} \int_0^2 r e^{r^2} dr d\theta \\
& = 2\pi \left(\frac{1}{2} e^{r^2} \right) \Big|_0^2 = 2\pi \cdot \frac{1}{2} (e^4 - 1) = \pi(e^4 - 1).
\end{aligned}$$

b. Recall that Stokes' theorem applies to the integral of the curl of a vec. field. So we want to write \vec{F} as the curl of another field, $\vec{F} = \nabla \times \vec{A}$ for some \vec{A} .

$$\nabla \cdot \vec{F} = \partial_x F_1 + \partial_y F_2 + \partial_z F_3$$

$$= z \sin yz - z \sin yz + 0 = 0$$

so since \vec{F} is defined on \mathbb{R}^3 , \vec{F} has a vector potential \vec{A} (that is, $\vec{F} = \nabla \times \vec{A}$)
(see also: Poincaré's lemma)

Hence by Stokes' theorem,

$$\iint_S \vec{F} \cdot d\vec{S} = \iint_S (\nabla \times \vec{A}) \cdot d\vec{S} = \int_{\partial S} \vec{A} \cdot d\vec{\sigma} = - \int_D \vec{A} \cdot d\vec{\sigma}$$

$$= - \iint_D \vec{F} \cdot d\vec{S} = -\pi(e^4 - 1) \quad \text{from part (a).}$$

4a. For the side, $S(u, v) = (\cos u, \sin u, v) \quad 0 \leq u \leq 2\pi, 0 \leq v \leq 1$

$$\partial_u S = (-\sin u, \cos u, 0)$$

$$\partial_v S = (0, 0, 1)$$

$$\vec{N} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ -\sin u & \cos u & 0 \\ 0 & 0 & 1 \end{vmatrix} = (\cos u, \sin u, 0)$$

$$\begin{aligned} \iint_{\text{side}} \vec{F} \cdot d\vec{S} &= \int_0^{2\pi} \int_0^1 (\cos u \sin u, v \sin u, v \cos u) \cdot (\cos u, \sin u, 0) \, dv \, du \\ &= \int_0^{2\pi} \int_0^1 \cos^2 u \sin u + v \sin^2 u \, dv \, du \\ &= \int_0^{2\pi} \underbrace{\cos^2 u \sin u}_{\frac{d}{du}(-\frac{1}{3} \cos^3 u)} \, du + \frac{1}{2} \int_0^{2\pi} \sin^2 u \, du = \frac{\pi}{2} \end{aligned}$$

For the top disc, $(r \cos \theta, r \sin \theta, 1)$ has $\vec{N} = (0, 0, r)$,

$$\iint_{\text{top}} \vec{F} \cdot d\vec{S} = \int_0^{2\pi} \int_0^1 r^2 \cos \theta \, dr \, d\theta = 0$$

$$\text{& sim. } \iint_{\text{bottom}} \vec{F} \cdot d\vec{S} = 0. \quad \text{So} \quad \iint_W \vec{F} \cdot d\vec{S} = \frac{\pi}{2}.$$

$$b. \quad \nabla \cdot \vec{F} = \partial_x(xy) + \partial_y(yz) + \partial_z(xz) = y + z + x$$

$$\iiint_W (\nabla \cdot \vec{F}) \, dV = \int_0^{2\pi} \int_0^1 \int_0^1 (z + r(\cos \theta + \sin \theta)) r \, dr \, dz \, d\theta = \frac{\pi}{2}.$$

c. These are the same (which also follows from the Divergence Theorem).